

Geometric Quantum Gates, Composite Pulses, and Trotter-Suzuki Formulas

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Introduction

composite quantum gates

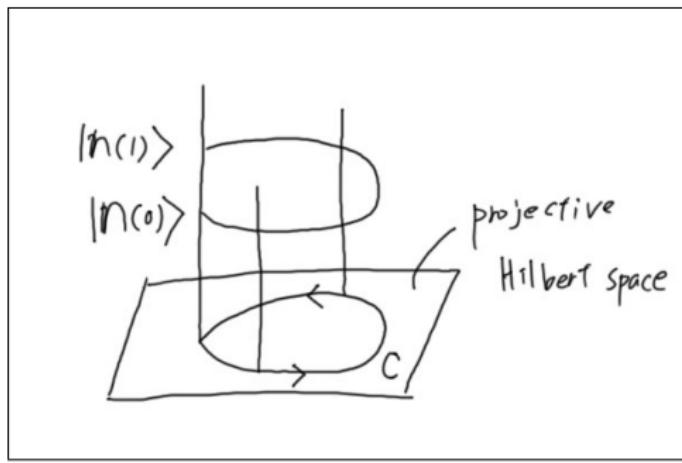
$$\prod_{j=1}^N R(\mathbf{m}_j, \theta_j) = R(\mathbf{m}, \theta)$$

fully compensating composite quantum gate

$$\prod_{j=1}^N R(\mathbf{m}_j, \theta_j(1 + \varepsilon)) = R(\mathbf{m}, \theta) + \underline{O(\varepsilon^2)}$$

Geometric Quantum Gates

phases



$$|n(1)\rangle = \underline{e^{i\gamma}} |n(0)\rangle \quad , \quad \gamma = \gamma_d + \gamma_g$$

γ_d : dynamic phase , γ_g : geometric phase

Geometric Quantum Gates

geometric phase:

$$\gamma_g = i \int_0^1 \langle \mathbf{n}(t) | \frac{d}{dt} |\mathbf{n}(t)\rangle dt$$

dynamic phase:

$$\gamma_d = - \int_0^1 \langle \mathbf{n}(t) | H |n(t)\rangle dt$$

H : Hamiltonian

Composite Pulse

single-qubit operations

$$R(\mathbf{m}, \theta) = \exp\left(-i\theta \frac{\mathbf{m} \cdot \boldsymbol{\sigma}}{2}\right)$$

θ : control field strength , \mathbf{m} : axis of rotation ($|\mathbf{m}| = 1$)

$$\boldsymbol{\sigma} = (\sigma_x, \sigma_y, \sigma_z)$$

error in θ

$$R(\mathbf{m}, \theta(1 + \varepsilon)) = R(\mathbf{m}, \theta) + O(\varepsilon)$$

Composite Pulse

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Composite Pulse

composite quantum gates

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Composite Pulse

composite quantum gates

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fully compensating composite quantum gate

$$\prod_{j=1}^N R(\mathbf{m}_j, \theta_j(1 + \varepsilon)) = R(\mathbf{m}, \theta) + \underline{O(\varepsilon^2)}$$

Composite Pulse

single-qubit operation

$$R(\mathbf{m}, \theta) = \exp\left(-i \frac{\theta}{2} \mathbf{m} \cdot \boldsymbol{\sigma}\right) \iff H(\mathbf{m}, \theta) = \frac{\theta}{2} \mathbf{m} \cdot \boldsymbol{\sigma}$$

Hamiltonian

dynamic phase

$$\underline{\gamma_d = - \int_0^1 \langle n | H(m, \theta) | n \rangle = - \frac{\theta}{2} m \cdot n}$$

n : Bloch vector , $|n\rangle$: state vector

$$n = \langle n | \sigma | n \rangle$$

Composite Pulse

single-qubit operation

$$R(\mathbf{m}, \theta) = \exp\left(-i \frac{\theta}{2} \mathbf{m} \cdot \boldsymbol{\sigma}\right) \iff H(\mathbf{m}, \theta) = \frac{\theta}{2} \mathbf{m} \cdot \boldsymbol{\sigma}$$

Hamiltonian

dynamic phase

$$\underline{\gamma_d = - \int_0^1 \langle \mathbf{n} | H(\mathbf{m}, \theta) | \mathbf{n} \rangle = - \frac{\theta}{2} \mathbf{m} \cdot \mathbf{n}}$$

\mathbf{n} : Bloch vector , $|\mathbf{n}\rangle$: state vector

$$\mathbf{n} = \langle \mathbf{n} | \boldsymbol{\sigma} | \mathbf{n} \rangle$$

Composite Pulse and Dynamic Phase

systematic control field strength error

$$\begin{aligned} \prod_{j=1}^N R(\mathbf{m}_j, \theta_j(1 + \varepsilon)) &= R(\mathbf{m}, \theta) + \sum_{j=1}^N R_N \dots R_j \left(-i\varepsilon \frac{\theta_j}{2} \mathbf{m}_j \cdot \boldsymbol{\sigma} \right) \dots R_1 + O(\varepsilon^2) \\ &= R(\mathbf{m}, \theta) - i\varepsilon \sum_{j=1}^N R_N \dots (R_j H_j) \dots R_1 + O(\varepsilon^2) \end{aligned}$$

$$R_j = R(\mathbf{m}_j, \theta_j) = \exp \left(-i\theta_j \frac{\mathbf{m}_j \cdot \boldsymbol{\sigma}}{2} \right)$$

$$H_j = H(\mathbf{m}_j, \theta_j) = \frac{\theta_j}{2} \mathbf{m}_j \cdot \boldsymbol{\sigma}$$

Composite Pulse and Dynamic Phase

expectation value

$$\begin{aligned}
 -\langle \mathbf{n}_0 | \sum_{j=1}^N R_N \dots R_j H_j R_{j-1} \dots R_1 | \mathbf{n}_0 \rangle &= -e^{-i\theta/2} \sum_{j=1}^N \langle \mathbf{n}_{j-1} | H_j | \mathbf{n}_{j-1} \rangle \\
 &= -e^{-i\theta/2} \sum_{j=1}^N \gamma_{d,j}
 \end{aligned}$$

$$\sum_{j=1}^N \gamma_{d,j} = 0 \quad \Rightarrow \quad \prod_{j=1}^N R(\mathbf{m}_j, \theta_j(1 + \varepsilon)) = \underline{R(\mathbf{m}, \theta) + O(\varepsilon^2)}$$

composite quantum gate is robust against
control field strength error.

SCROFULOUS pulse

SCROFULOUS pulse

$$R(\mathbf{m}_1, \theta_1) R(\mathbf{m}_2, \pi) R(\mathbf{m}_1, \theta_1) = R(\mathbf{x}, \theta)$$

$$\mathbf{m}_i = (\cos \phi_i, \sin \phi_i, 0)$$

SCROFULOUS pulse

condition 1

$$\langle \mathbf{x} | R(\mathbf{m}_1, \theta_1) R(\mathbf{m}_2, \pi) R(\mathbf{m}_1, \theta_1) | \mathbf{x} \rangle = e^{-i\theta/2}$$

$$\Rightarrow \cos \theta_1 = \frac{\tan(\phi_1 - \phi_2)}{\tan \phi_1} , \quad \sin \frac{\theta}{2} = \frac{\sin(\phi_1 - \phi_2)}{\sin \phi_1}$$

condition 2

$$\sum_{j=1}^3 \langle \mathbf{n}_{j-1} | H_j | \mathbf{n}_{j-1} \rangle = 0$$

$$\Rightarrow 2\theta_1 \cos(\phi_1 - \phi_2) + \pi = 0$$

same as H. K. Cummins, G. Llewellyn, and J. A. Jones, Phys. Rev. A 67, 042308 (2003).

SCROFULOUS pulse

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Trotter-Suzuki Formula

Trotter-Suzuki formula

when $B = \sum A_l$,

$$\exp(-iBt) = \prod_l \exp(-iA_lt) + O(t^2)$$

A : series of Hamiltonian

B : Hamiltonian

Composite Pulse based on Trotter-Suzuki Formula

$$R(\mathbf{x}, \theta)$$

erroneous rotation

$$R(\mathbf{x}, \theta(1 + \varepsilon)) = R(\mathbf{x}, \theta) \underline{R(\mathbf{x}, \theta\varepsilon)}$$

if $\prod_j R_j = R(\mathbf{x}, -\theta\varepsilon)$,

$$\left(\prod_j R_j \right) R(\mathbf{x}, \theta) \longrightarrow \text{reliable quantum gate}$$

Composite Pulse based on Trotter-Suzuki Formula

Trotter-Suzuki formula

$$\exp(-iBt) = \prod_l \exp(-iA_l t) + O(t^2)$$

$$R(\mathbf{x}, -\theta\varepsilon) = \exp \left[-i \left(-\theta \frac{\sigma_x}{2} \right) \varepsilon \right]$$

$$= \prod_{l=1}^N \exp(-iA_l \varepsilon) + O(\varepsilon^2)$$

where

$$\sum_{l=1}^N A_l = -\theta \frac{\sigma_x}{2}$$

Composite Pulse based on Trotter-Suzuki Formula

Now we set $N = 2$.

$$A_l \longrightarrow A_+, A_-$$

For example,

$$A_{\pm} = -2\pi \frac{\mathbf{m}_{\pm} \cdot \boldsymbol{\sigma}}{2}$$

$$\mathbf{m}_{\pm} = (\cos \phi, \pm \sin \phi, 0), \quad \phi = \cos^{-1} \left(\frac{\theta}{4\pi} \right)$$



$$R(\mathbf{m}_+, -2\pi(1 + \varepsilon))R(\mathbf{m}_-, -2\pi(1 + \varepsilon)) = \underline{\exp(-iA_+\varepsilon) \exp(-iA_-\varepsilon)}$$

$R(\mathbf{m}_+, -2\pi)R(\mathbf{m}_-, -2\pi)R(\mathbf{x}, \theta) \implies \text{reliable quantum gate}$

Composite Pulse based on Trotter-Suzuki Formula

condition

$$A_+ + A_- = -\theta \frac{\sigma_x}{2}$$

$$0 = \theta \frac{\sigma_x}{2} + A_+ + A_-$$

$$= \langle \mathbf{x} | \theta \frac{\sigma_x}{2} + A_+ + A_- | \mathbf{x} \rangle$$

$$= \langle \mathbf{x} | \theta \frac{\sigma_x}{2} | \mathbf{x} \rangle + \langle \mathbf{x} | R(\mathbf{x}, -\theta) A_- R(\mathbf{x}, \theta) | \mathbf{x} \rangle$$

$$+ \langle \mathbf{x} | R(\mathbf{x}, -\theta) R(\mathbf{m}_-, 2\pi) A_+ R(\mathbf{m}_-, -2\pi) R(\mathbf{x}, -\theta) | \mathbf{x} \rangle$$

condition for using Trotter-Suzuki formula

$$A_+ + A_- = -\theta \frac{\sigma_x}{2}$$

=

$$\sum_j \gamma_{dj} = 0$$

Summary

- All GQG with Aharonov-Anandan phases are fully compensating composite quantum gates that are robust against control field strength errors.
- The condition for using the Trotter-Suzuki formulas is equivalent that the sum of dynamic phases in a composite quantum gate is vanishing.